




# Hand-Motion Controlled Doodle Jump

TEAM 07

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01

**Introduction**

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# Features

1. Full Motion-Controlled Game
2. Application of Image and Voice Processing
3. FPGA-based Real-time Interactive Game



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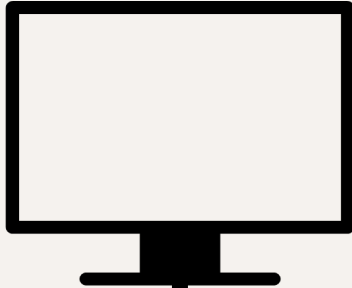
02

**Structures**

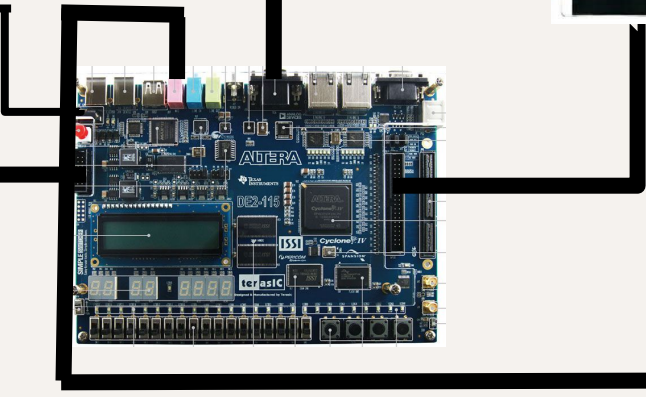
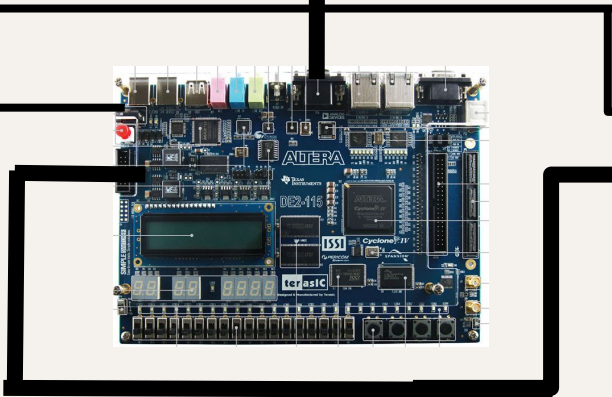
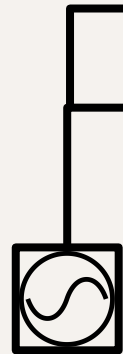
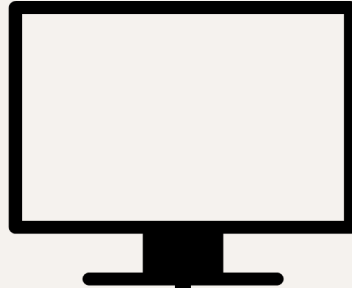


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Doodle Jump  
Game Display



Hand Motion  
Display



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# Hand Motion Detection

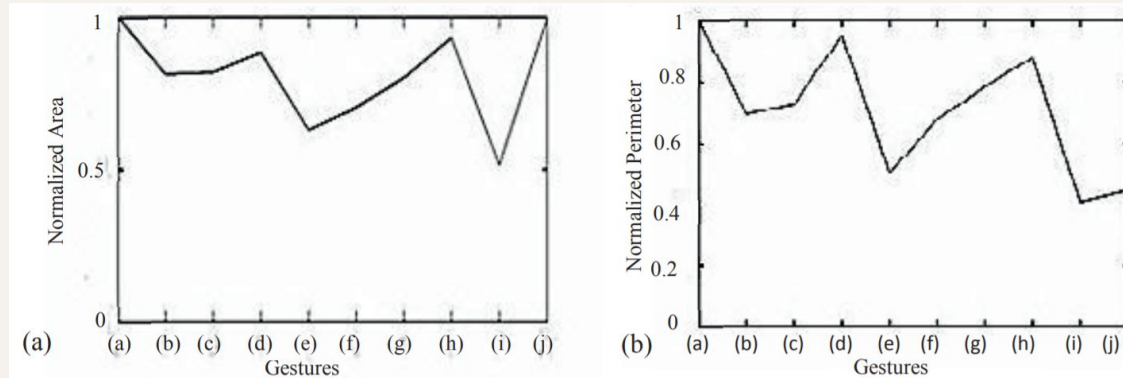
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# Related Works

FPGA based Real Time Human Hand Gesture Recognition System

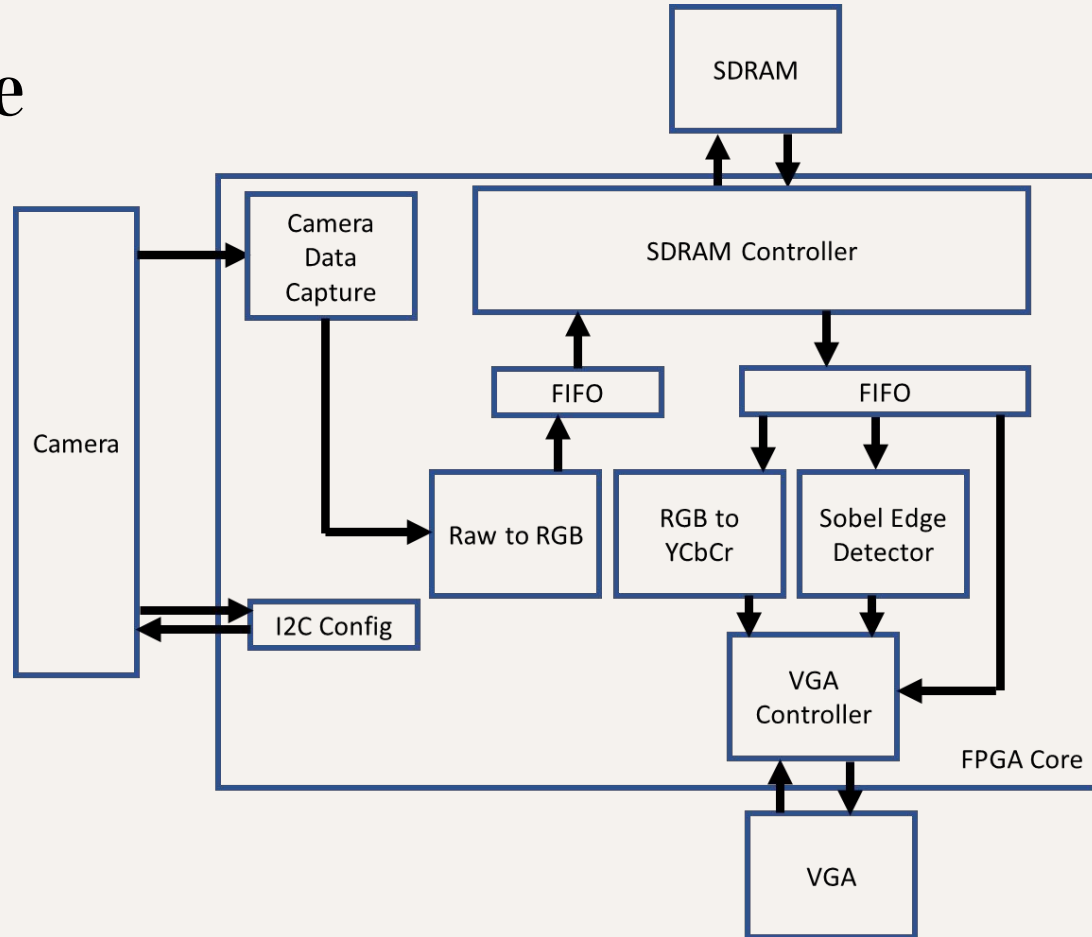
$$\text{Area of Hand} = \sum_{x=0}^{W-1} \sum_{y=0}^{H-1} I(x, y) (\text{segmented})$$

$$\text{Perimeter of Hand} = \sum_{x=0}^{W-1} \sum_{y=0}^{H-1} \text{Edge}(I(x, y))$$





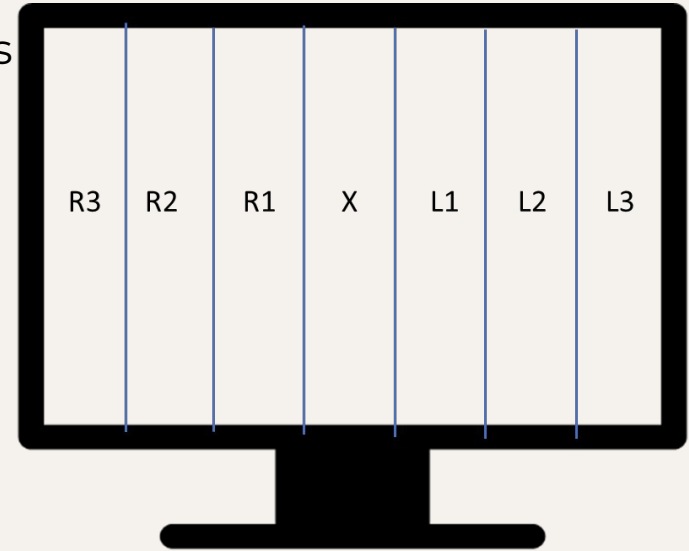
# Structure



# Skin Color Detection

1. Detect skin color pixels( $133 \leq Cr < 180$  and  $91 \leq Cb < 112$ )
2. Find sections with the most skin color pixels
3. Send signals according to which section it is

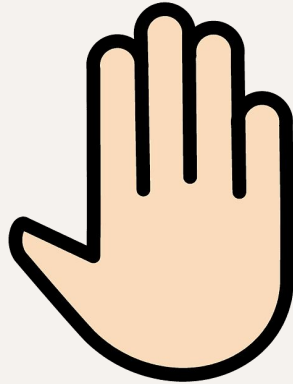
(L: Go left, X: Stay, R: Go Right)



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# Gesture Detection

1. Edge detection for skin color pixels
2. Count edge pixel amounts to distinguish gestures



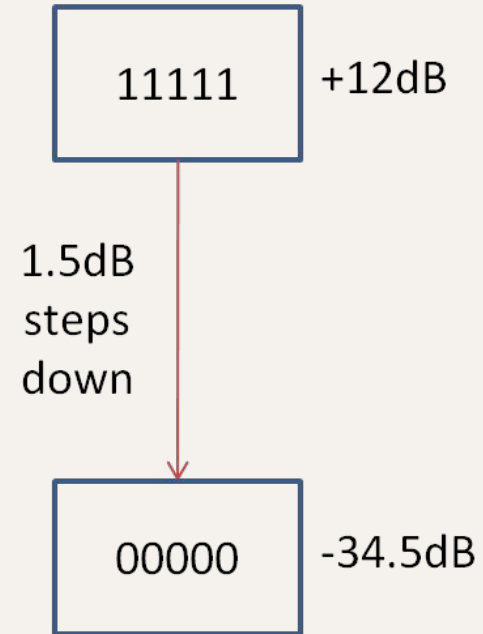
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# Volume Detection

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# Volume Logic

1. WM8731 - 16-bit audio data input
2. [14:10] Line Input Volume



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03

Implementation

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# RGB to YCbCr

$$Y = (0.257 * R) + (0.504 * G) + (0.098 * B) + 16$$

$$Cr = (0.439 * R) - (0.368 * G) - (0.071 * B) + 128$$

$$Cb = - (0.148 * R) - (0.291 * G) + (0.439 * B) + 128$$

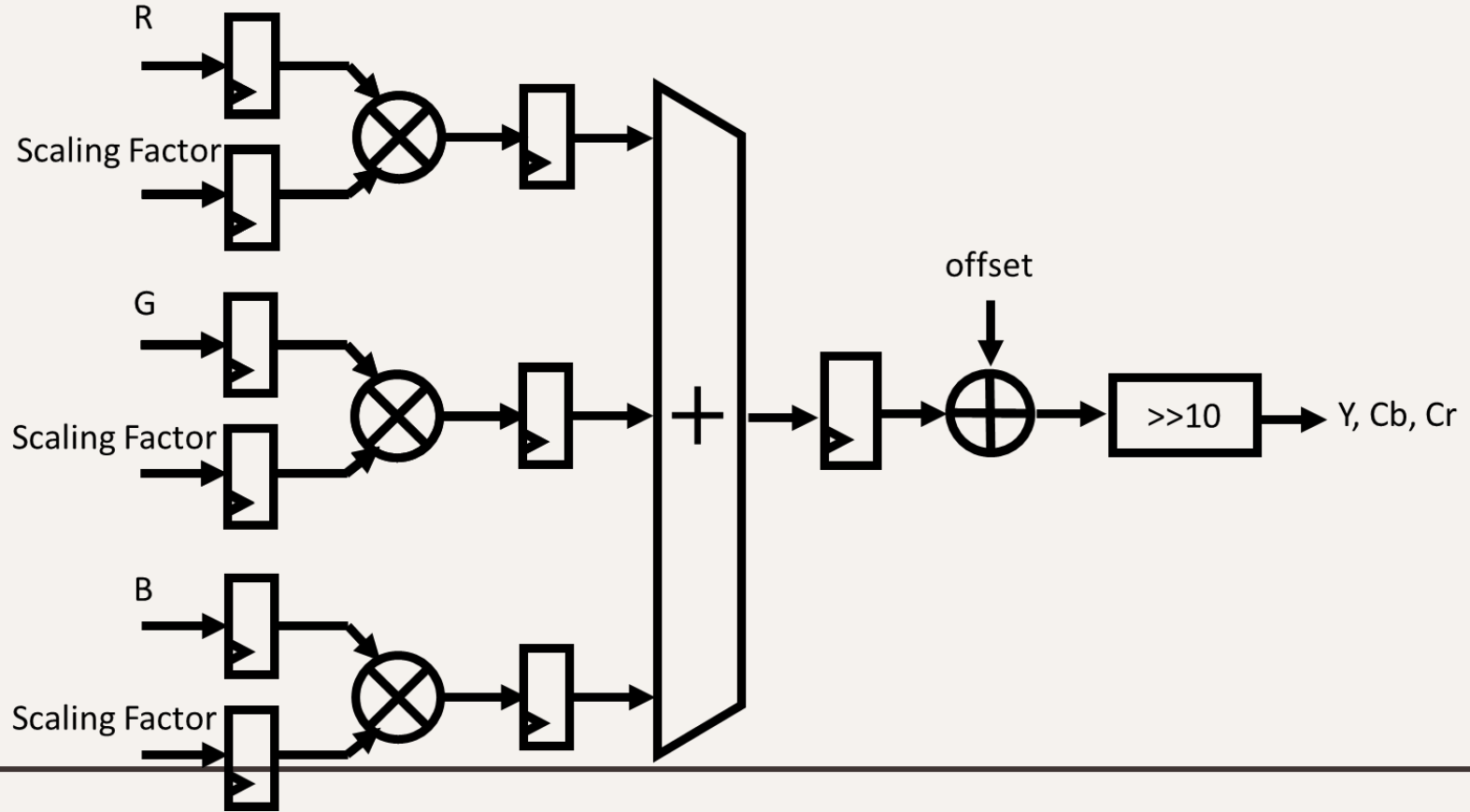
Digital Representation:

$$Y \ll 10 = (263 * R) + (516 * G) + (100 * B) + 16384$$

$$Cr \ll 10 = (450 * R) - (377 * G) - (731 * B) + 131072$$

$$Cb \ll 10 = - (152 * R) - (299 * G) + (450 * B) + 131072$$

# RGB to YCbCr





# Skin Color Detection Result



# Sobel Edge Filter

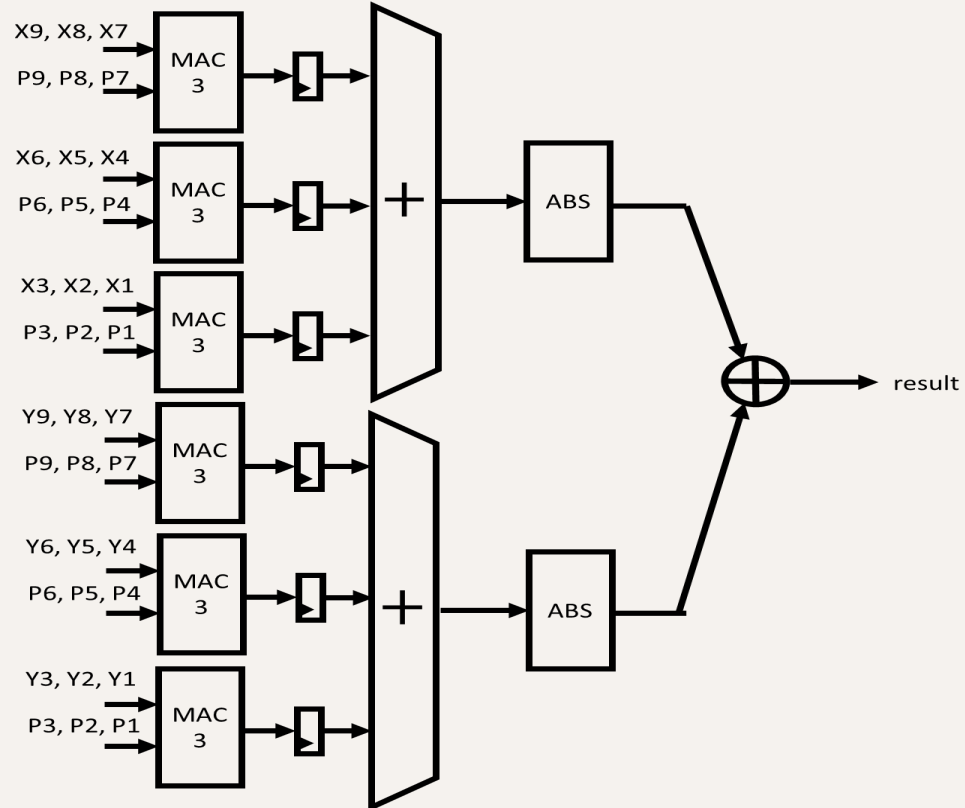
G<sub>x</sub>

-1	0	+1
-2	0	+2
-1	0	+1

G<sub>y</sub>

+1	+2	+1
0	0	0
-1	-2	-1

# Sobel Edge Detector



# Edge Detection

## Binary

Adjustable  
threshold to  
binarize the image

## Skin Color Segmentation

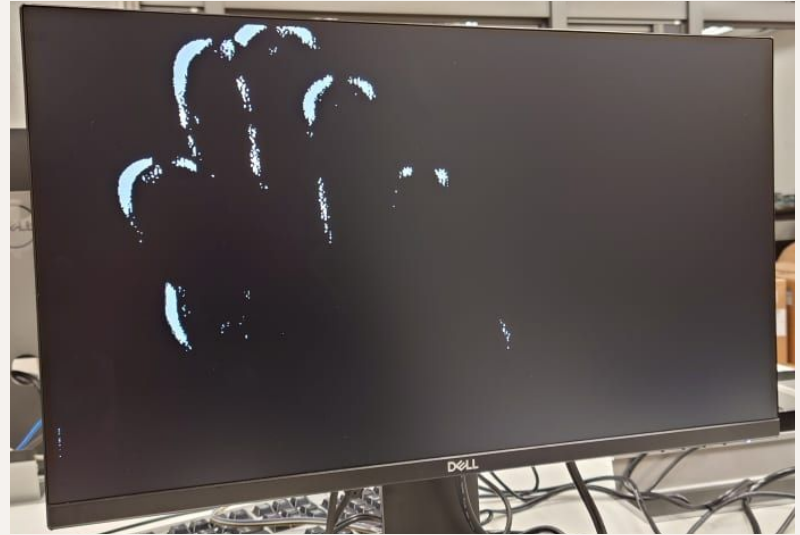
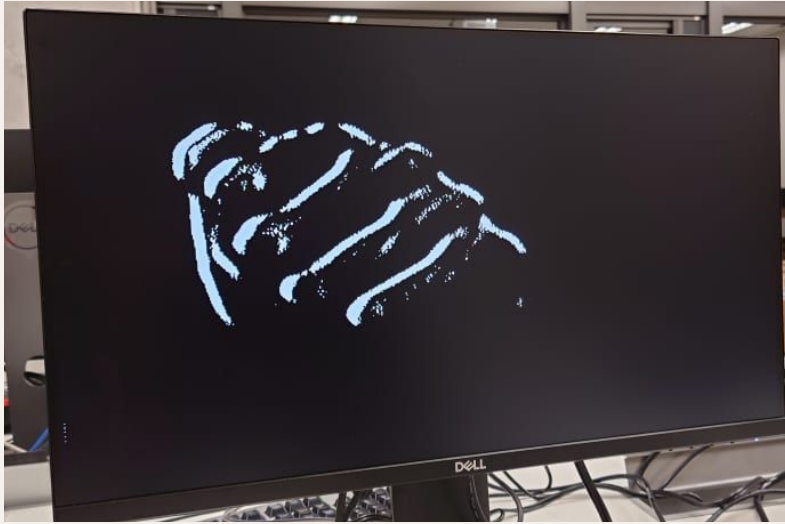
Delete  
non-skin-colored  
pixels

## Purify

Set center pixel to 0  
if all surrounding  
pixels are 0

0	1	2
3	4	5
6	7	8

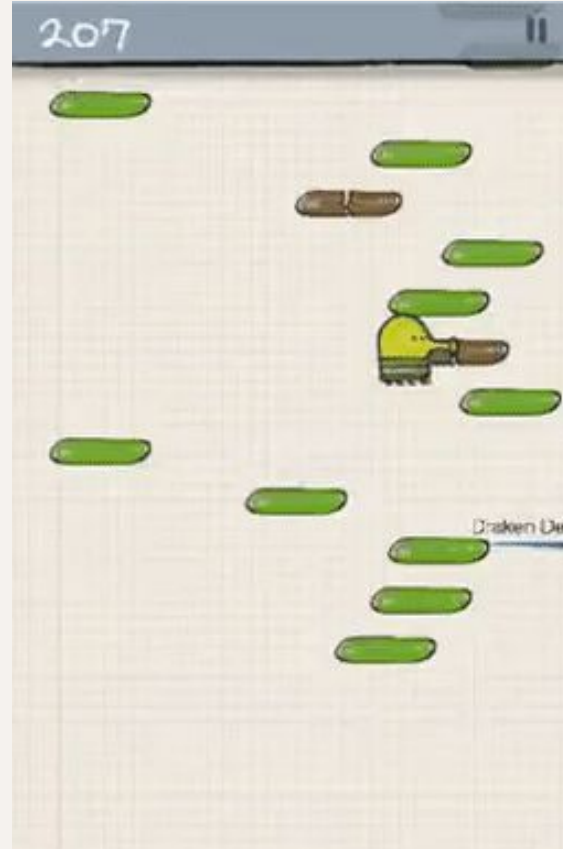
# Edge Detection Result



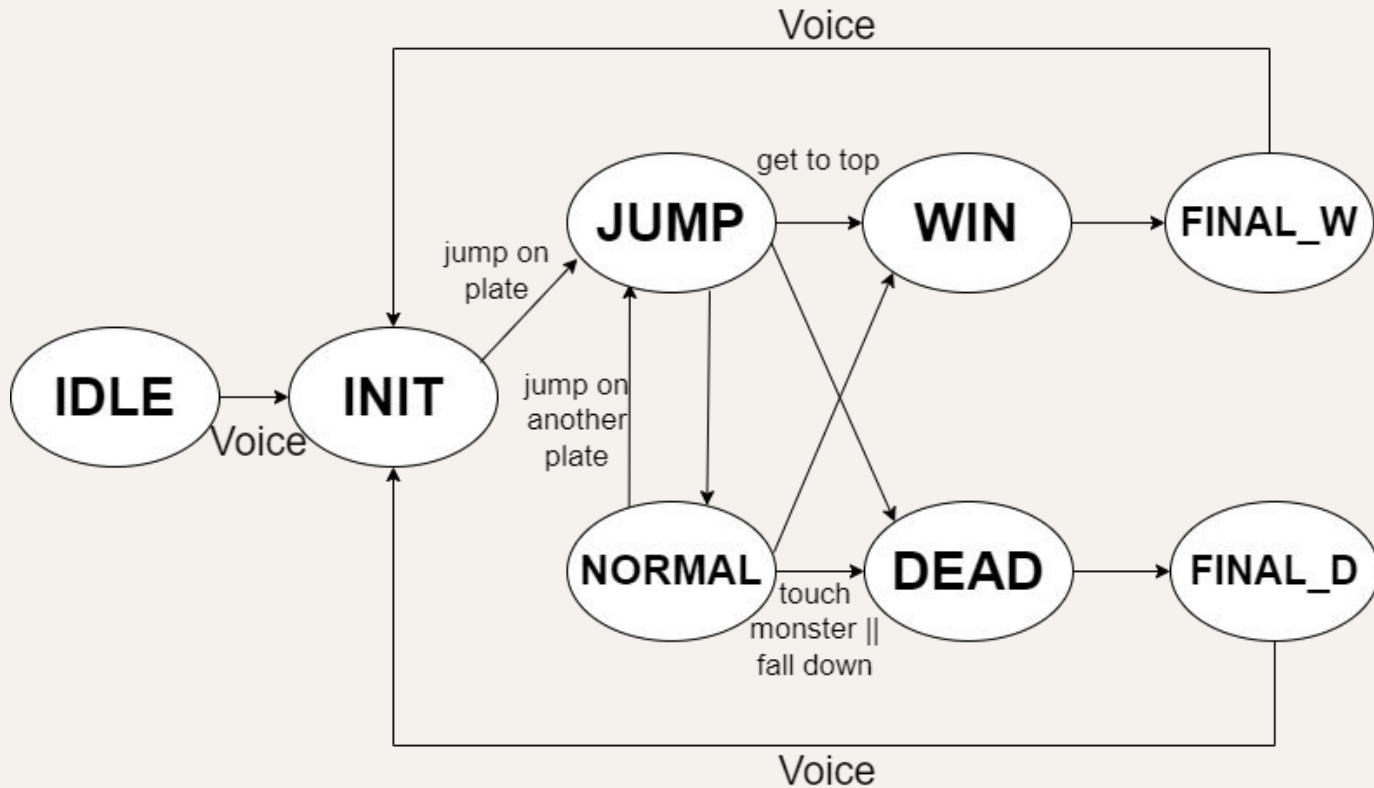
# Game Design

## Doodle Jump

- Direction control
- Fire bullet
- Start / Restart



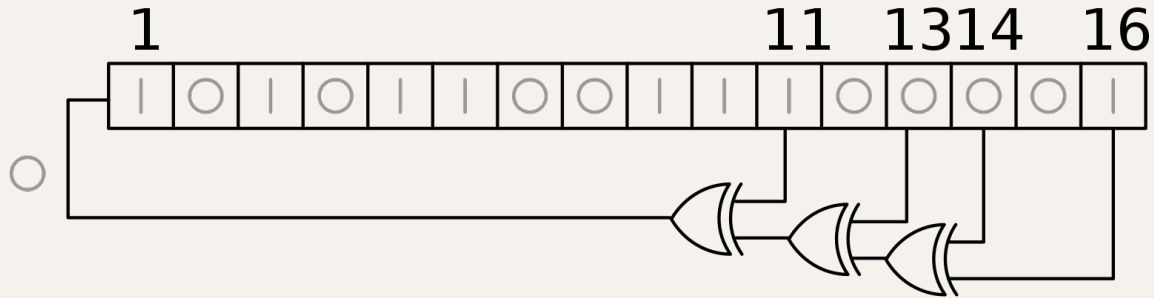
# Game FSM



# Random Level

Fibonacci Linear-Feedback Shift Register

- Cycle:  $2^{16} - 1$







**DEMO**



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04

**Difficulties**

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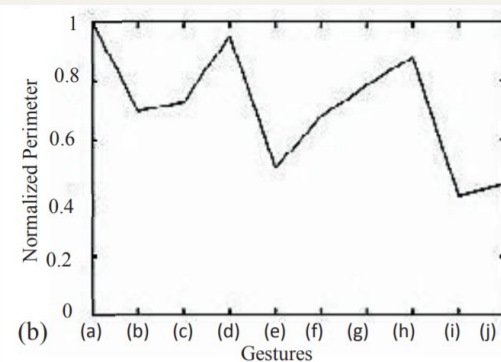
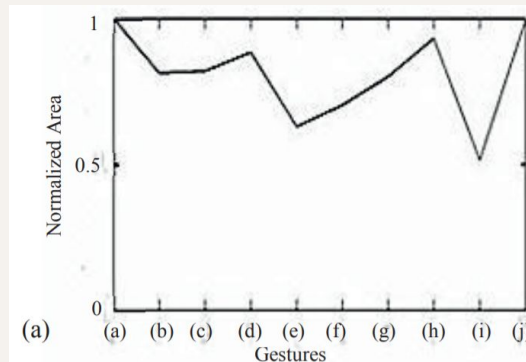
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# Difficulties

- Estimating PERIMETER of hand via Edge Detection can be inaccurate if the background is not homogeneous.
  - **Solution:** Only consider skin color pixels for estimating PERIMETER.
-

# Difficulties

- Calculating the ratio of  $(PERIMETER^2)$  and AREA of the hand can lead to distance-proof result for gesture distinguishment.
- PERIMETER and AREA are postively correlated. Calculating the ratio will reduce the difference for distinguishing gestures, especially for real time distinguishing.
- **Solution:** Only consider PERIMETER of hand for gesture distinguishing and limit the player's distance from camera.



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# Difficulties

- The clocks of two FPGAs are asynchronous and have different frequencies, which may cause errors when the signal triggering
  - The clock frequencies are 12MHz and 25MHz
  
  - **Solution:** Make the triggering signal stay longer (2 or 3 cycles) to make sure the other FPGA receive it correctly
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# Reference

- Design of Color Recognition System Based on FPGA

[https://www.researchgate.net/publication/303481540\\_Design\\_of\\_Color\\_Recognition\\_System\\_Based\\_on\\_FPGA](https://www.researchgate.net/publication/303481540_Design_of_Color_Recognition_System_Based_on_FPGA)

- Digital Camera: OV7670 CMOS camera + DE2-115 FPGA board + LandTiger 2.0 board

[http://www.dejazzer.com/eigenpi/digital\\_camera/digital\\_camera.html](http://www.dejazzer.com/eigenpi/digital_camera/digital_camera.html)

- User Manual-CMOS TRDB-D5M Camera and 8MB SDRAM A2V4S40CTP

[https://home.isr.uc.pt/~jfilipe/files/User\\_Manual\\_EN\\_Group11.pdf?fbclid=IwAR07VRjNEj02Ty9CvWN6vitdExqpl85Tfx9x\\_j9xednEXKcfrZKz4iilT7l](https://home.isr.uc.pt/~jfilipe/files/User_Manual_EN_Group11.pdf?fbclid=IwAR07VRjNEj02Ty9CvWN6vitdExqpl85Tfx9x_j9xednEXKcfrZKz4iilT7l)

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